We consider time evolution using 'time-dependent variational principle' (TDVP)

1. 1-site TDVP [Haegeman2016, App. B]
tangent space of MPS having one

Schrödinger equation for MPS:

$$
\begin{equation*}
i \frac{d}{d t}|\bar{\psi}[M(t)]\rangle=\hat{H}|\bar{\psi}[m(t)]\rangle \tag{1}
\end{equation*}
$$ updated tensor


space of MPS with specified dimensions

if we insist on using MPS with fixed bond dimensions, left side has following form:

Each term differs from $|\Psi(t\rangle\rangle$ by precisely one site tensor or on bond tensor, so left side is a state in the tangent space, $\mathbb{V}^{15}$ of $|\Psi(t)\rangle$. But right side of $(1)$ is not, since since $H|\Psi(t)\rangle$ can have larger bond dimensions than $\mid \Psi(\{ \rangle\rangle$.

So, project right side of (1) to $V^{1 s}$ : $\left.\left.\quad i \frac{d}{d t}|\underline{\psi}[M(t)]\rangle \underset{\hat{\lambda}}{\approx} \hat{p}^{1 s} \hat{H} \right\rvert\, \psi[m(t)]\right)$ tangent space approximation

Left and right sides of (4) are structurally consistent. To see this, consider bond $\ell$
Left side of (4) contains:

$$
\begin{equation*}
\frac{d}{d t} \frac{A_{l} \Lambda_{l} B_{l+1}}{40 \frac{p}{p}}=\frac{\dot{A}_{l} \Lambda_{l} B_{l+1}}{4}+\frac{A_{l} \dot{\Lambda}_{l} B_{l+1}}{4}+\frac{A_{l} \Lambda_{l} \dot{B}_{l+1}}{p} \tag{5}
\end{equation*}
$$

Decompose: $\dot{A}_{l}=A_{l} \Lambda_{l}^{\prime}+\bar{A}_{l} \bar{\Lambda}_{l}^{\prime}, \quad B_{l+1}=\Lambda_{l}^{\prime \prime} B_{l+1}+\bar{\Lambda}^{\prime \prime} \bar{B}_{l+1}$
Then we find:

Right side of (4) requires tangent space projector. Consider its form (TS-I.5.25):


The three terms with $\bar{l}=l, \quad l^{\prime}=l, \quad \bar{l}=l+1$, applied to , $\hat{H}|\bar{\Psi}(t)\rangle$, yield

matching structure of (7). Thus, $p^{1 s}$, applied to $H(\Psi(t))$, yields terms of precisely the right structure!

To integrate projected Schrödinger eq. (4), we write tangent space projector in the form (TS-I.5.26):
and write (4) as




Right side is sum of terms, each specifying an update of one $\psi_{l}^{\text {ls }}$ or $\psi_{l}^{\frac{1}{b}}$ on the left. Eq. (4) can be integrated one site at a time, by defining the updates through the following local Schrödinger equations:


In site-canonical form, site $\ell$ involves two terms linear in $C_{l}: \quad i C_{l}(t)=H_{l}^{1 S} C_{l}(t)$
Their contribution can be integrated exactly: replace $C_{e}(t)$ by $\quad C_{l}(t+\tau)=e^{-i H_{l}^{\prime S} \tau} C_{l}(t) \quad(1 /)$

In bond-canonical form, site $\ell$ involves two terms linear in $\Lambda_{l}: \quad i \Lambda_{l}(t)=-H_{l}^{b} \Lambda_{l}(t) \quad(15)$

Their contribution can be integrated exactly: replace $\Lambda_{\ell}$
(t) by $\Lambda_{e}(t-\tau)=e^{i H_{l}^{b} \tau} \Lambda_{l}(t)$

In practice, $e^{-i H_{l}^{\prime S} \tau} C_{l}$ and $e^{i H_{l}^{b} \tau} \Lambda_{l} \quad$ are computed by using Krylov methods.
Build a Krylov space by applying $H_{l}^{1 s}$ multiple times to $C_{l}$, set up the tridiagonal representation $\left[\mathrm{H}_{l}^{\text {cs }}\right]_{\text {Krylov }}$ of $H_{l}^{1 / s}$ in this basis, then compute the matrix exponential in this basis, and apply result to $C_{l}$.
Likewise for $H_{l}^{b}$ and $\Lambda_{l}$.

To successively update entire chains, alternate between site- and bond-canonical form, propagating forward or backward in time with $H_{\ell}^{15}$ or $H_{\ell}^{b}$, respectively:

$$
C_{1}(t):=2
$$

1. Forward sweep, for $l=1, \ldots, \mathcal{L}-1 \quad$, starting from

$$
\begin{equation*}
B_{1}(t) B_{2}(t) \ldots B_{\mathcal{L}}(t) \tag{17}
\end{equation*}
$$

$$
\begin{aligned}
& C_{e}(t) B_{l+1}(t) \\
& \xrightarrow[H_{l(a)}^{(s)}]{H_{l}^{(s)}} C_{e}(t+\tau) B_{l+1}^{1(b)}(t) \\
& =\overbrace{A_{l}(t+\tau) \widetilde{\Lambda}_{l}(t+\tau) B_{l+1}(t)}
\end{aligned}
$$



$$
\xrightarrow[I(c)]{\stackrel{H_{l}^{b}}{\longrightarrow}} A_{l}(t+\tau) \underbrace{\hat{\Lambda}_{l}(t) B_{l+1}(t)}_{l(d)}
$$

$$
=A_{l}(t+\tau) C_{l+1}(t)
$$

until we reach last site, and MPS described by
2. Turn around: $C_{\mathcal{L}}(t)$

3. Backward sweep, for $\ell=\mathcal{L}-1, \ldots, 1$, starting from $A_{1}(t+\tau) \ldots A_{\mathcal{L}-1}(t+\tau) C_{\mathcal{L}}(t+2 \tau)$

$$
A_{\ell}(t+\tau) C_{\ell+1}(t+2 \tau)
$$

$$
\begin{array}{lll}
t+2 \tau \uparrow  \tag{21}\\
t+\tau- & A & A \\
t & Y & M
\end{array}
$$

$$
\begin{aligned}
& \xrightarrow[2(a)]{H_{\mathcal{L}}^{1 s}} C_{\mathcal{L}}(t+\tau) \\
& \xrightarrow[2(6)]{H_{\mathcal{L}}^{15}} C_{\mathcal{L}}(t+2 \tau)
\end{aligned}
$$

$$
A_{\ell}(t+\tau) C_{\ell+1}(t+\tau \tau)
$$

$$
=A_{l(a)}(t+\tau) \tilde{\Lambda}_{l}(t+2 \tau) B_{l+1}(t+2 \tau)
$$

$\xrightarrow[3(c)]{H_{l}^{b}} \underbrace{A_{l}(t+\tau)}_{3(c)} \hat{\Lambda}_{l}(t+\tau) B_{l+1}(t+2 \tau)$
$=C_{l}(t+\tau) B_{\ell+1}(t+2 \tau)$
$\xrightarrow[3(\alpha)]{H_{l}^{15}} C_{l}(t+2 \tau) B_{l+1}(t+2 \tau)$
until we reach first site, and MPS described by


The scheme described above involves 'one-site updates'. This has the (major!) drawback (as in one-site DMRG), that it is not possible to dynamically explore different symmetry sectors. To overcome this drawback, a 'two-site update' version of tangent space methods can be set up [Haegemann2016, App. C].

A systematic comparison of various MPS-based time evolution schemes has been performed in [Paeckel2019]. Conclusion: 2-site-update tangent space scheme is most accurate!

A scheme for doing 1-site TDVP while nevertheless expanding bonds, called 'controlled bond expansion (CBE), was proposed in [Li2022] (see next lecture!).

The construction of tangent space $V^{1 / 3}$ and its projector $P^{1 / 3}$ can be generalized to $n$ sites [Gleis2022a]. We focus on $n=2$ (but general case is analogous). Define space of 2-site variations:

$$
\begin{align*}
\mathbb{V}^{2 s} & =\text { span of all states }\left|\Psi^{\prime}\right\rangle \text { differing from }|\Psi\rangle \text { on precisely } 2 \text { neighboring sites } \\
& =\operatorname{span}\left\{\left|\Psi^{\prime}\right\rangle=\right.  \tag{I}\\
\text { formal definition: } & =\operatorname{span}\left\{\operatorname{im}_{\operatorname{im}_{\text {image }}}\left(P_{\ell}^{2 s}\right) \mid \ell \in[1, \mathcal{L}-1]\right\} \tag{2}
\end{align*}
$$

Recall:


Global $2 s$ projector $\hat{P}^{2 s}$, such that $\mathbb{V}^{2 s}=\operatorname{im}\left(P^{2 s}\right)$, can be found with a Gram-Schmidt scheme analogous to our construction of $\hat{P}^{\text {'s }}$, see [Gleis2022a]:
compare (TS-I.5.22)



All summand are mutually orthogonal, ensuring that $\left(P^{2 s}\right)^{2}=P^{2 s}$, and that $P^{23} P_{R^{\prime}}^{25}=P_{\ell^{\prime}}^{25}$.
Alternative expression:
compare (TS-I.5.26)


This projector is used for 2-site TDVP (see TS-II.3)

## Orthogonal n-site projectors

For any given MPS $|\bar{\Psi}[M]\rangle$, full Hilbert space of chain can be decomposed into mutually orthogonal subspaces:

$$
\begin{equation*}
\mathbb{V}=V_{1} \omega \cdots \mathbb{V}_{\mathcal{L}}=\oplus_{n=0}^{\mathcal{L}} V^{n_{\perp}} \tag{8}
\end{equation*}
$$

with $\mathbb{V}^{0+}:=\mathbb{V}^{0 S}:=\operatorname{span}\{|\Psi\rangle\}$
'irreducible' $\mathbb{V}^{n \perp}$ is complement of $\mathbb{V}^{(n-1) s}$ in $\mathbb{V}^{n s}=\mathbb{V}^{(n-1) s} \oplus \mathbb{V}^{n \perp}$
(10) $=$ span of states differing from $\mid \Psi$ ) on $\eta$ contiguous sites, not expressible through subsets of $u^{\prime}<u$ sites Correspondingly, identity can be decomposed as:

$$
\begin{equation*}
\mathbb{I}_{V}=\mathbb{1}_{d}^{\otimes R}=\sum_{\substack{n=0 \\ \text { completeness }}}^{\mathcal{L}} p n^{n}, \quad p n_{1} p n_{\perp}^{\prime}=\delta^{n n^{\prime}} p n^{\prime} \tag{II}
\end{equation*}
$$

where $p \nsim$ is defined as the projector having $\mathbb{V}^{n \perp}$ as image: $\quad \operatorname{im}(p n \downarrow)=\mathbb{V}^{n \perp}$

$$
\text { POL }=\text { pOS }=|\Psi\rangle\langle\psi|=\frac{1-1}{\frac{1}{y}+\frac{1}{y}+\lambda}
$$

$n \geq 1: p^{n L}:=p^{n s}\left(\mathbb{1}_{v}-p^{(n-1) s}\right)=p^{k s}-p^{(n-1) s}$

Consider $\mathrm{n}=1$ :

$$
\text { since } \begin{align*}
\left.\mathbb{V}^{(n-1) s}\right) \subset \mathbb{V}^{u s} & \Rightarrow \operatorname{im}\left(p^{(n-1) s}\right)<i m\left(p^{n s}\right)  \tag{14}\\
& \Rightarrow p^{n s} p^{(n-1) s}=p^{(n-1) s}
\end{align*}
$$

$$
p^{\prime 1}=p^{1 s}-p^{\circ s}
$$

choose $\ell^{\prime}=\mathcal{L}$
projects onto all 1-site variations orthogonal to $|\Psi\rangle$
( 16 )
(TS-I.4.17) $P_{\ell+1}^{0 S}$
Consider $\mathrm{n}=2$ :

$$
\begin{align*}
& p^{21}=p^{2 s}-p s=\left(\sum_{l=1}^{\mathcal{L}-1} p_{l}^{2 s}-\sum_{l=2}^{\mathcal{L}-1} p_{l}^{1 s}\right)-\left(\sum_{l}^{\mathcal{L}}\right.  \tag{17}\\
& =\sum_{l=1}^{\mathcal{L}-1}\left(p_{l}^{2 s}-p_{l+1}^{1 s}-p_{l}^{1 s}+p_{l+1}^{0 s}\right)
\end{align*}
$$

(TS-I.3.28)

very important result! (20)

2 -site tangent space methods are analogous to 1 -site methods, but use a 2 -site projector. There is a conceptual difference, though: the main reason for using 2 -site schemes is that they allow sectors with new quantum numbers to be introduced if the action of H requires this. However, states with different ranges of quantum numbers live in different manifolds, hence this procedure 'cannot easily be captured in a smooth evolution described using a differential equation. However, like most numerical integration schemes, the aforementioned algorithm is intrinsically discrete by choosing a time step, and it poses no problem to formulate an analogous two-site algorithm'. [Haegeman2016, Sec. V]. In other words: the tangent space approach is conceptually not as clean for the 2 -site as for the 1 -site scheme.

Schrödinger equation, projected onto 2 -site tangent space, now takes the form

$$
i \frac{d}{d t}|\psi[M(t)]\rangle=\hat{\rho}^{2 s} \hat{H}|\psi[m(t)]\rangle
$$



This yields [compare (1.11)]:




Right side is sum of terms, each specifying an update of one $\psi_{l}^{2 s}$ or $\psi_{l}^{1 s}$ on the left. Eq. (4) can be integrated one site at a time, by defining the updates through the following local Schrödinger equations:


Right side is sum of terms, each linear in a factor appearing on the left. Can be integrated one site at a time:
In 2-site-canonical form, site $\ell$ involves two terms linear in $\psi_{l}^{2 s}: \quad i \psi_{l}^{2 s}(t)=H_{l}^{2 s} \psi_{l}^{2 s}(t)$
Their contribution can be integrated exactly: replace $\psi_{l}^{2 s}(t)$ by $\quad \psi_{l}^{2 s}(t+\tau)=e^{-i H_{l}^{2 s} \tau} \psi_{l}^{2 s}(t)$ forward time step

In 1-site-canonical form, site $\ell+1$ involves two terms linear in $\psi_{l+i}^{1 /}: \quad i \quad \psi_{l+1}^{1 s}(t)=-H_{l+1}^{1 s} \psi_{l+1}^{1 s}(t)$ Their contribution can be integrated exactly: replace $\psi_{l+1}^{(s)}(t)$ by $\quad \psi_{l+1}^{(s)}(t-\tau)=e^{i H_{l+1}^{(s} \tau} \psi_{l+1}^{(s)}(t)$

Their contribution can be integrated exactly: replace $\psi_{l+1}^{(s}(t)$ by $\quad \psi_{l+1}^{(s}(t-\tau)=e^{i H_{l+1}^{(s} \tau} \psi_{l+1}^{(s)}(t) \quad$ (3)

To successively update entire chains, alternate between 2-site- and 1-site-canonical form, propagating forward or backward in time with $H_{\ell}^{2 s}$ or $H_{l}^{15}$, respectively (analogously to 1-site scheme).

A systematic comparison of various MPS-based time evolution schemes has been performed in [Paeckel2019]. Conclusion: 2-site-update tangent space scheme is most accurate!

When doing MPS computations involving SVD truncations of virtual bonds, the results should be computed for several values of the bond dimension, $D$, to check convergence as $D \rightarrow \infty$. Often it is also necessary to extrapolate the results to $D=\infty$, e.g. by plotting results versus $1 / D$ or some power thereof.


However, for some computational schemes, it is not a prior clear how the observable of interest scales with $D$, nor how it should be extrapolated to $D=\infty$. An example is ground state energy when computed using 1-site DMRG with subspace expansion [Hubig2015], because it does not rely on SVD truncation of bonds.

Thus, it is of interest to have a reliable error measure without requiring costly 2 -site DMRG. A convenient scheme was proposed in [Hubig2018], based on a smart way to approximate the full energy variance,

$$
\begin{aligned}
\Delta_{E}: & =\|(H-E) \psi\|^{2}=\langle\psi|(\hat{H}-E)^{2}|\psi\rangle & & \text { (= zero for an exact eigenstate) (1) } \\
& =\langle\psi| \hat{H}^{2}|\psi\rangle-E^{2}, & & \text { with } \quad E=\langle\psi| H|\psi\rangle
\end{aligned}
$$



Then extrapolations can be done by computing quantity of interested for several $D$, If quantity of interest is energy, then extrapolation is linear, $\quad E_{g}\left(\Delta_{E}\right)=E_{G}^{\text {exact }}+a \cdot \Delta_{E}$

Computing $\langle\psi| \hat{H}^{2}|\psi\rangle$ directly is costly for large systems with long-ranged interactions, such as 2 D systems treated by DMRG snakes. Also, computing $\Delta_{E}$ as the difference between two potentially large numbers is prone to inaccuracies. [Hubig2018] found a computation scheme in which the subtraction of such large numbers is avoided a prior.


Key idea: use projectors $P^{И_{\perp}}$ onto mutually orthogonal, irreducible spaces $V^{u_{\perp}}$
 with $P^{\circ \perp}=|\Psi\rangle\langle\Psi|$

Insert completeness into definition of variance:

$$
\begin{equation*}
\left.\Delta_{E} \stackrel{(4)}{=}\langle\psi|(\hat{H}-E) \sum_{n=0}^{\mathcal{L}} p^{n \mathcal{1}}(\hat{H}-E)\right)|\psi\rangle=: \sum_{n=0}^{\mathcal{L}} \Delta_{E}^{n \perp} \tag{8}
\end{equation*}
$$

Now two crucial simplifications occur:

$$
\begin{equation*}
\Delta_{\hat{E}}^{0 \perp} \stackrel{(5)}{=}\langle\psi|(\hat{H}-E) \underbrace{|\psi\rangle\langle\psi|}_{\text {(b) } 0 \perp}(\hat{H}-E))|\psi\rangle=(E-E\rangle(E-E)={ }_{\text {largest contribution to variance cancels by construction! }} \tag{9}
\end{equation*}
$$

$n>0$

$$
\begin{align*}
\left.\Delta_{E}^{n_{1}}=\langle\psi|(\hat{H}-E) P^{n \perp}(\hat{H}-E)\right)|\psi\rangle= & \langle\psi| \hat{H} \underbrace{P^{n \perp}} \hat{H}|\psi\rangle \text {, since } p^{(n>0\rangle \perp}|\psi\rangle \stackrel{(5,6)}{=} p^{(T S-I I .2 .11)} \tag{10}
\end{align*}
$$

$$
\begin{equation*}
=\left\|p^{n \perp} \hat{H} \psi\right\|^{2} \tag{II}
\end{equation*}
$$

In practice, approximate $\Delta_{E}$ by the first two nonzero terms:

$$
\begin{equation*}
\Delta_{E} \simeq \Delta_{E}^{2 S}=\Delta_{E}^{11}+\Delta_{E}^{2 \perp}=\langle\psi| \hat{H} p^{15} \hat{H}|\psi\rangle+\langle\psi| \hat{H} P^{2 s} \hat{H}|\psi\rangle \tag{12}
\end{equation*}
$$

(11) is exact if longest-range terms in $\hat{H}$ are nearest-neighbor, because then $p(n \geqslant 3) \perp 1 \hat{H}|\Psi\rangle=0$

Explicit computations:


We would like to avoid computing ${ }_{d}^{D}$ explicitly, because of its large image dimension.
So rewrite, using isometry condition for discarded sector: $\quad \square=C$
and completeness of kept together with discarded isometries: $\left.\frac{\Delta}{T}=>1-\frac{\lambda}{T} \right\rvert\,$ (18)


$$
\begin{align*}
& \Delta_{E}^{1 L}=\langle\psi| \hat{H} P^{1 \perp} \hat{H}|\psi\rangle=\|p 1 \perp H \psi\|^{2}=\sum_{l=1}^{\mathcal{L}}\left\|P_{l, l+1}^{D k} H \psi\right\|^{2} \tag{15}
\end{align*}
$$

 $\qquad$
(19)

$$
\begin{align*}
& \Delta_{E}^{2 \perp}=\langle\psi| \hat{H}{\underset{p}{ }}_{2 \perp}^{p^{2 \perp}} \hat{H}|\psi\rangle \quad=\left\|p^{2 \perp} H \psi\right\|^{2}=\sum_{l=1}^{L-1}\left\|P_{l, l+1}^{D} H \psi\right\|^{2}  \tag{21}\\
& =\sum_{l=1}^{\mathcal{L}-1} \mid \tag{23}
\end{align*}
$$

