

V Tensor network methods

So far, we only considered exact representations of states in the many-body Hilbert space, facing us with an exponential increase in computational complexity with the number of degrees of freedom.

Now we explore approximate representations of states $|\Psi\rangle \in \mathcal{H}_L$ such that for a set of parameters $\underline{t} = (t_1, t_2, \dots, t_p)$ with $p \in \mathbb{N}$, the approximation $|\tilde{\Psi}(\underline{t})\rangle$ is optimal in the sense:

For a given approx. quality $\varepsilon > 0$ there exist $p \in \mathbb{N}$ with $p \sim \mathcal{O}(L^\alpha)$ for some $\alpha \in \mathbb{N}$ such that

$$\underline{t} \in \bigvee_{\mathbb{K}}^p \Rightarrow \text{dist}(|\Psi\rangle, |\tilde{\Psi}(\underline{t})\rangle) < \varepsilon$$

Questions:

- (i) How do optimal parametrizations $|\tilde{\Psi}(\underline{t})\rangle$ look like for which choices of $\text{dist}(X, Y)$?
- (ii) What do exponents α look like?
- (iii) Classification of states with respect to α ?

(iv) Can we construct algorithms to solve eigenvalue problem in manifold of parametrizations $|\hat{\psi}(t)\rangle$?

Consider the state $|\psi\rangle \in \mathcal{H}_2$ with $\alpha \in [0, \frac{\pi}{2})$:

$$|\psi\rangle = \cos(\alpha) |\uparrow\downarrow\rangle + \sin(\alpha) |\downarrow\uparrow\rangle$$

$$\equiv \sum_{\sigma_1, \sigma_2} \psi_{\sigma_1, \sigma_2} |\sigma_1, \sigma_2\rangle \quad \text{with } \sigma_{1/2} \in \{\uparrow, \downarrow\}$$

Let us interpret $\psi_{\sigma_1, \sigma_2}$ as matrix:

$$\begin{aligned} \underline{\psi} &= \begin{matrix} & \sigma_2 & \uparrow & \downarrow \\ \begin{matrix} \sigma_1 \\ \uparrow \\ \downarrow \end{matrix} & \begin{pmatrix} 0 & \cos(\alpha) \\ \sin(\alpha) & 0 \end{pmatrix} \end{matrix} \\ &= \underbrace{\begin{matrix} \sigma_1 \\ \uparrow \\ \downarrow \end{matrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}_{\underline{U}} \underbrace{\begin{pmatrix} \cos(\alpha) & 0 \\ 0 & \sin(\alpha) \end{pmatrix}}_{\underline{S}} \underbrace{\begin{matrix} \uparrow & \downarrow \\ \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \end{matrix}}_{\underline{V}}^{\sigma_2} \\ &= \begin{pmatrix} -u_1^t \\ -u_2^t \end{pmatrix} \underline{S} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \underline{V} \end{aligned}$$

This suggests to write the matrix element $\psi_{\sigma_1, \sigma_2}$:

$$\psi_{\uparrow\uparrow} = \underline{u}_1^t \underline{S} \underline{v}_1 ; \quad \psi_{\uparrow\downarrow} = \underline{u}_1^t \underline{S} \underline{v}_2 ; \quad \psi_{\downarrow\uparrow} = \underline{u}_2^t \underline{S} \underline{v}_1 ; \quad \psi_{\downarrow\downarrow} = \underline{u}_2^t \underline{S} \underline{v}_2$$

or for the state $|4\rangle$:

$$|4\rangle = \sum_{\sigma_1=1}^2 \sum_{\sigma_2=1}^2 u_{\sigma_1}^t \underline{S} \underline{V}_{\sigma_2} |\sigma_1, \sigma_2\rangle$$

Note:

(i) From $\underline{U}^t \underline{U} = \mathbb{1}_{2 \times 2}$ & $\underline{V} \underline{V}^t = \mathbb{1}_{2 \times 2}$ we can connect \underline{S} to the eigenvalues of the reduced density matrices:

$$\hat{\rho}_{<2} = \text{Tr}_{\sigma_2} |4\rangle \langle 4|$$

$$= \sum_{\sigma_2=1}^2 \langle \sigma_2 | \sum_{\sigma_1'} \sum_{\sigma_2'} u_{\sigma_1'}^t \underline{S} \underline{V}_{\sigma_2'} |\sigma_1', \sigma_2'\rangle \langle \sigma_1'' \sigma_2'' | \underline{V}_{\sigma_2''}^t \underline{S} u_{\sigma_1''} | \sigma_2 \rangle$$

$$= \sum_{\sigma_1', \sigma_1''} u_{\sigma_1'}^t \underline{S} \underbrace{\sum_{\sigma_2} \underline{V}_{\sigma_2} \underline{V}_{\sigma_2}^t}_{\mathbb{1}_{2 \times 2}} \underline{S} u_{\sigma_1''} |\sigma_1'\rangle \langle \sigma_1''|$$

$$= \sum_{\sigma_1', \sigma_1''} u_{\sigma_1'}^t \underline{S}^2 u_{\sigma_1''} |\sigma_1'\rangle \langle \sigma_1''| \quad (*)$$

$$\equiv \sum_{m=1}^2 |u_m\rangle \delta_m \langle u_m|$$

$$\text{with } |u_m\rangle = \sum_{\sigma_1} u_{\sigma_1}^t |\sigma_1\rangle$$

analogue:

$$\hat{\rho}_{12} = \text{Tr}_{\mathcal{H}_1} |\Psi\rangle\langle\Psi| = \sum_{m=1}^2 |V_m\rangle S_m \langle V_m|$$

(*) is eigenvalue decomposition of $\hat{\rho}_{12}$ ($\hat{\rho}_{12}$)

(ii) From $\underline{u} \underline{u}^\dagger = \mathbb{1}_{2 \times 2}$ & $\underline{v} \underline{v}^\dagger = \mathbb{1}_{2 \times 2}$ it also follows

that

$$|\Psi\rangle = \sum_{m=1}^2 S_m |u_m\rangle |v_m\rangle$$

is the Schmidt decomposition of $|\Psi\rangle$

(iii) If we sort S_m such that $S_1 > S_2$ & neglect S_2 , then the approx. $|\tilde{\Psi}\rangle = S_1 |u_1\rangle |v_1\rangle$ is the best rank-1 approx. to $|\Psi\rangle$ w.r.t. $\|\cdot\|_2$ norm of the distance of the reduced density matrices:

$$\begin{aligned} \|\hat{\rho}_{12} - \hat{\tilde{\rho}}_{12}\|_2 &= \text{Tr} \left((\hat{\rho}_{12} - \hat{\tilde{\rho}}_{12})^2 \right) \\ &= \text{Tr} \left(\left(\sum_{m=1}^2 S_m |u_m\rangle\langle u_m| - S_1 |u_1\rangle\langle u_1| \right)^2 \right) \\ &= \text{Tr} \left(S_2^2 |u_2\rangle\langle u_2| \right) = S_2^2 \end{aligned}$$

$$\text{\& analogue: } \|\hat{\rho}_{12} - \hat{\tilde{\rho}}_{12}\|_2 = \text{Tr} \left(\left(\sum_{m=1}^2 S_m |v_m\rangle\langle v_m| - S_1 |v_1\rangle\langle v_1| \right)^2 \right) = S_2^2$$

This motivates us to introduce "local" representations of wavefunction coefficients, i.e., tensor networks!

V.1 Matrix-product states / Tensor trains

From the previous considerations, we define a matrix product state (MPS) by decomposing the coefficients $\psi_{\sigma_1, \sigma_2, \dots, \sigma_L}$ of a state $|\psi\rangle \in \mathcal{H}_L$ in the many-body Hilbert space $\mathcal{H}_L = \mathcal{H}_{d_1} \otimes \dots \otimes \mathcal{H}_{d_L}$ describing $L \in \mathbb{N}$ degrees of freedom with local dimensions $d_j \in \mathbb{N}$ as:

$$\psi_{\sigma_1, \dots, \sigma_L} = \underline{M}^{\sigma_1} \underline{M}^{\sigma_2} \dots \underline{M}^{\sigma_{L-1}} \underline{M}^{\sigma_L} \in \mathbb{K}$$

where $\underline{M}^{\sigma_j} \in V_{\mathbb{K}}^{m_{j-1} \times m_j}$ are matrices for $j \in \{2, \dots, L-1\}$

& $\underline{M}^{\sigma_1} \in V_{\mathbb{K}}^{1 \times m_1}$, $\underline{M}^{\sigma_L} \in V_{\mathbb{K}}^{m_L \times 1}$ are row / column vectors.

We call $m_j \in \mathbb{N}$ the bond dimension of the MPS, which specify the number of parameters

used to represent

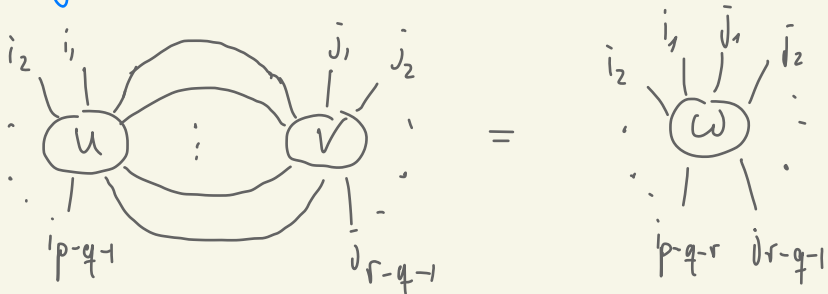
$$|4\rangle = \sum_{\sigma_1=1}^{d_1} \dots \sum_{\sigma_L=1}^{d_L} \underline{M}^{\sigma_1} \underline{M}^{\sigma_2} \dots \underline{M}^{\sigma_{L-1}} \underline{M}^{\sigma_L} |\sigma_1 \dots \sigma_L\rangle$$

Tensor network notation

Let $T_{i_1 \dots i_p}$ be a rank- p tensor with dimensions $d_1, \dots, d_p \in \mathbb{N}$. We denote $T_{i_1 \dots i_p}$ graphically:



Contractions over a set of q shared indices of two tensors $U_{i_1 \dots i_{p-q-1} n_1 \dots n_q}$, $V_{j_1 \dots j_{r-q-1} n_1 \dots n_q}$ are represented graphically as:



$$W_{i_1 \dots i_{r-q-1}}^{i_1 \dots i_{p-q-1}} = \sum_{n_1 \dots n_q} U_{n_1 \dots n_q}^{i_1 \dots i_{p-q-1}} V_{i_1 \dots i_{r-q-1}}^{n_1 \dots n_q}$$

Fusions are defined as grouping & merging of indices:

$$\begin{array}{c}
 i_1 \quad \quad i_p \\
 \diagdown \quad \diagup \\
 \textcircled{T} \\
 \diagup \quad \diagdown \\
 i_2 \quad \quad i_{p-1}
 \end{array}
 = (i_1 \dots i_{p-1}) \equiv \textcircled{T} - i_p$$

$$\overline{T}_{i_1 \dots i_{p-1} i_p} = \overline{T}_{(i_1 \dots i_{p-1}) i_p}$$

Splits are the inverse operations to fusions.

Let us use that graphical notation to represent the MPS decomposition:

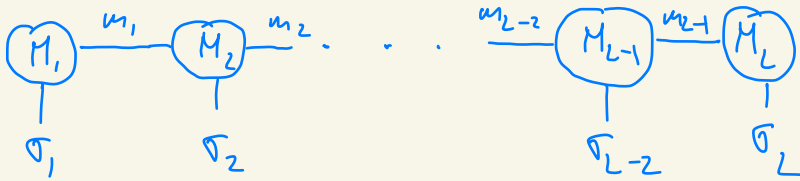
$$|\Psi\rangle = \sum_{\sigma_1} \dots \sum_{\sigma_L} \underline{M}^{\sigma_1} \underline{M}^{\sigma_2} \dots \underline{M}^{\sigma_{L-1}} \underline{M}^{\sigma_L} |\sigma_1 \dots \sigma_L\rangle$$

Identify: $\underline{M}^{\sigma_1} \rightarrow \textcircled{M_1} - \sigma_1$ a rank-2 tensor

$\underline{M}^{\sigma_j} \ (1 < j < L) \rightarrow \sigma_{j-1} - \textcircled{M_j} - \sigma_j$ a rank-3 tensor

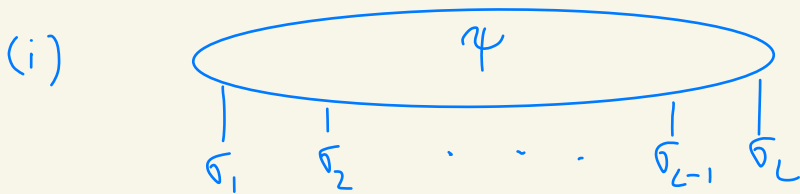
$$\underline{M}^{\sigma_L} \rightarrow m_{L-1} - \textcircled{M_L} \begin{array}{c} \text{a rank-2 tensor} \\ \downarrow \\ \sigma_L \end{array}$$

So that each coefficient $\psi_{\sigma_1, \dots, \sigma_L}$ is given by the network of contracted tensors:



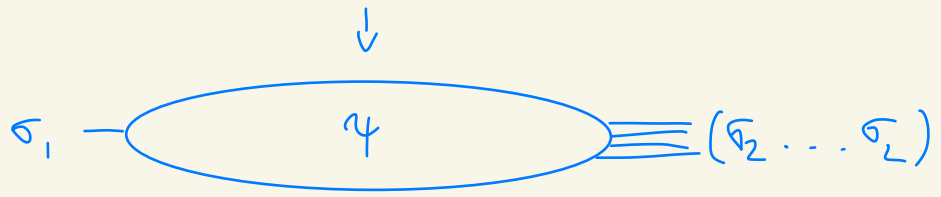
Can we always find an MPS representation for any $|\psi\rangle \in \mathcal{H}_L$?

Yes, if we apply the decomposition scheme introduced at the example of $|\psi\rangle = \cos(\alpha)|10\rangle + \sin(\alpha)|01\rangle$:



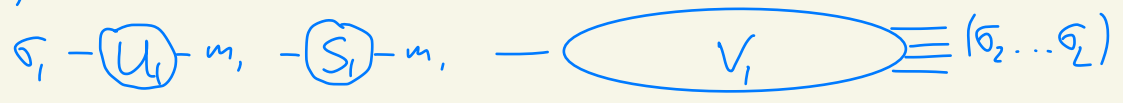
| Fuse

(ii)



(iii)

SVD



set $U_1 \equiv M_1$

contract $S_1 V_1 \equiv \psi'$

(iv)



& repeat from (i) until all local degrees of freedom σ_j are factored out.

Observations.

(i) at j 'th iteration, the number m_j of non-vanishing singular values S_{jn} , $n \in \{1, \dots, m_j\}$ determines the bond-dimensions m_j

(ii) Let $m \equiv \max_{j \in \{1, \dots, L\}} m_j$ & $d = \max_{j \in \{1, \dots, L\}} d_j$, then

the number of coefficients per site tensor is bounded by dm^2 . Thus in total the number of coefficients is bounded by:

$$2dm + \sum_{j=2}^{L-1} d_j m^2 \sim \mathcal{O}(Ldm^2)$$

(iii) In each bipartition, the approximation $|\tilde{\Psi}\rangle$ with max. bond dimension $m_0 \leq m$ yields the best approx. of the reduced density matrix w.r.t. $\|\cdot\|_2$ -norm.

Mixed-canonical form & gauge fixing

We consider a general MPS representation of a state $|\psi\rangle \in \mathcal{H}_L$ in the computational basis $\{|\sigma_1, \dots, \sigma_L\rangle\}$ where σ_j 's are labeling the local basis states, i.e., $\sigma_j \in \{0, \dots, d_j - 1\}$ with local dimensions $d_j \in \mathbb{N}$ for $j \in \{1, \dots, L\}$:

$$|\psi\rangle = \sum_{\sigma_1} \dots \sum_{\sigma_L} \underbrace{\underline{M}^{\sigma_1} \underline{M}^{\sigma_2} \dots \underline{M}^{\sigma_{L-1}} \underline{M}^{\sigma_L}}_{\Psi_{\sigma_1 \dots \sigma_L} \in \mathbb{K}} |\sigma_1, \dots, \sigma_L\rangle$$

with $\underline{M}^{\sigma_j} \in V_{\mathbb{K}}^{n_{j-1} \times n_j}$ matrices (or vectors at the edges).

The coefficient tensor $\Psi_{\sigma_1, \dots, \sigma_L}$ is invariant under gauge transformations of the form:

For $\underline{X} \in V_{\mathbb{K}}^{n_j \times n_j}$ an invertible matrix,

the MPS is invariant under the joint trafo:

$$\begin{array}{c} n_{j-1} \\ \circ \\ | \\ \sigma_j \\ | \\ n_j \end{array} \longrightarrow \begin{array}{c} n_{j-1} \\ \circ \\ | \\ \sigma_j \\ | \\ n_j \end{array} \boxed{X} \begin{array}{c} n_j \\ \circ \\ | \\ \sigma_j \\ | \\ n_j \end{array} \equiv \begin{array}{c} n_{j-1} \\ \circ \\ | \\ \sigma_j \\ | \\ n_j \end{array}$$

Defining :

(a) Left fusion : $M_{u_{j-1} u_j}^{\sigma_j} \mapsto M_{(\sigma_j u_{j-1}) u_j}$

$$u_{j-1} \text{---} \underset{\sigma_j}{\circ} \text{---} u_j \mapsto (\sigma_j u_{j-1}) \text{---} \circ \text{---} u_j$$

(b) Right fusion : $M_{u_{j-1} u_j}^{\sigma_j} \mapsto M_{u_{j-1} (\sigma_j u_j)}$

$$u_{j-1} \text{---} \underset{\sigma_j}{\circ} \text{---} u_j \mapsto u_{j-1} \text{---} \circ \text{---} (\sigma_j u_j)$$

The gauge conditions (i)/(ii) can be satisfied

by choosing \underline{X} as:

(i) $(\sigma_j u_{j-1}) \text{---} \circ \text{---} u_j \stackrel{M_j}{=} \stackrel{QR}{=} (\sigma_j u_{j-1}) \text{---} \triangleright \text{---} u'_j \text{---} \diamond \text{---} u_j$

$\Rightarrow \underline{X} = \underline{R}^{-1}$ which always exists because \underline{R} is upper triangular

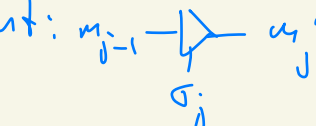
(ii) $u_{j-1} \text{---} \circ \text{---} (\sigma_j u_j) \stackrel{LQ}{=} u_{j-1} \text{---} \diamond \text{---} u'_{j-1} \text{---} \triangleleft \text{---} (\sigma_j u_j)$

$\Rightarrow \underline{X} = \underline{L}^{-1}$ which always exists because \underline{R} is upper triangular

Consequences:

- 1) The gauge transformations taking M_j to the left-/right-canonical form are unique, because QR(LQ)-decomposition is unique
- 2) For each M_j there is a unique gauge-trafo \underline{X} so that all gauge degrees of freedom of the MPS-representation can be fixed demanding all site-tensors to be either left- or right-canonical!
- 3) Replacing QR (LQ)-decomposition with the SVD, we immediately can read off $\underline{R}^{-1} / \underline{L}^{-1}$.

Notational agreement:

- (i) Left-canonical site-tensors are represented by triangles pointing to the right:
- 
- ②

& denoted by $A_{m_{j-1}}^{\sigma_j} m_j$

(ii) Right-canonical site-tensors are represented by triangles pointing to the left:

$$m_{j-1} \begin{array}{c} \leftarrow \\ \downarrow \\ \sigma_j \end{array} m_j$$

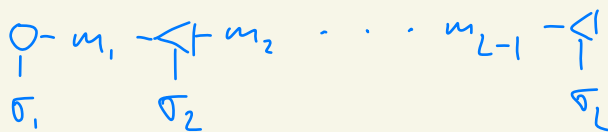
& denoted by $B_{m_{j-1}}^{\sigma_j} m_j$

* MPS of the form:



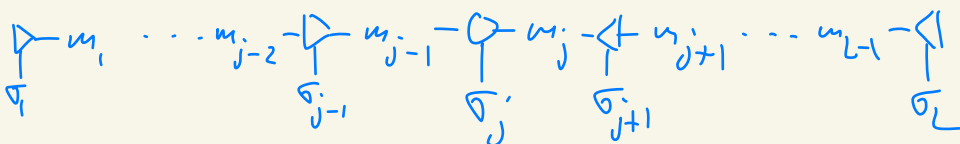
is called left-canonical

* MPS of the form:



is called right-canonical

A MPS of the form:

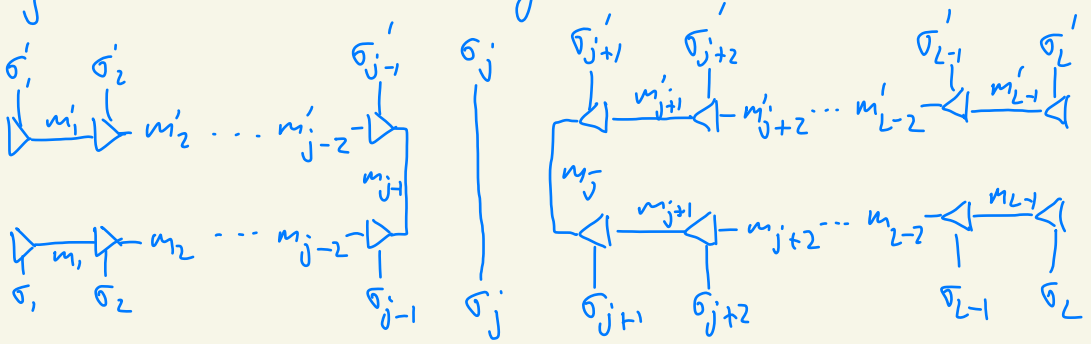


is called mixed-canonical with orthogonality center at site j .

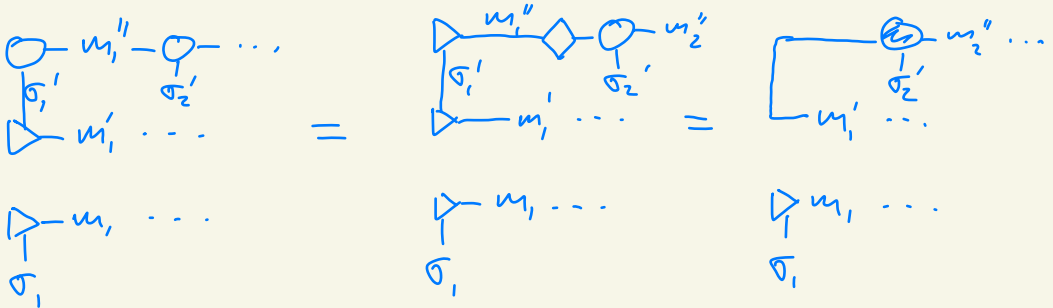
The gauge fixing projector

To formulate MPS - algorithms, it is convenient, to introduce the gauge fixing projector $\hat{\Pi}_j$.

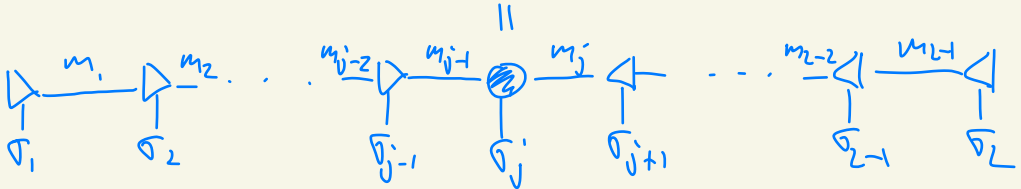
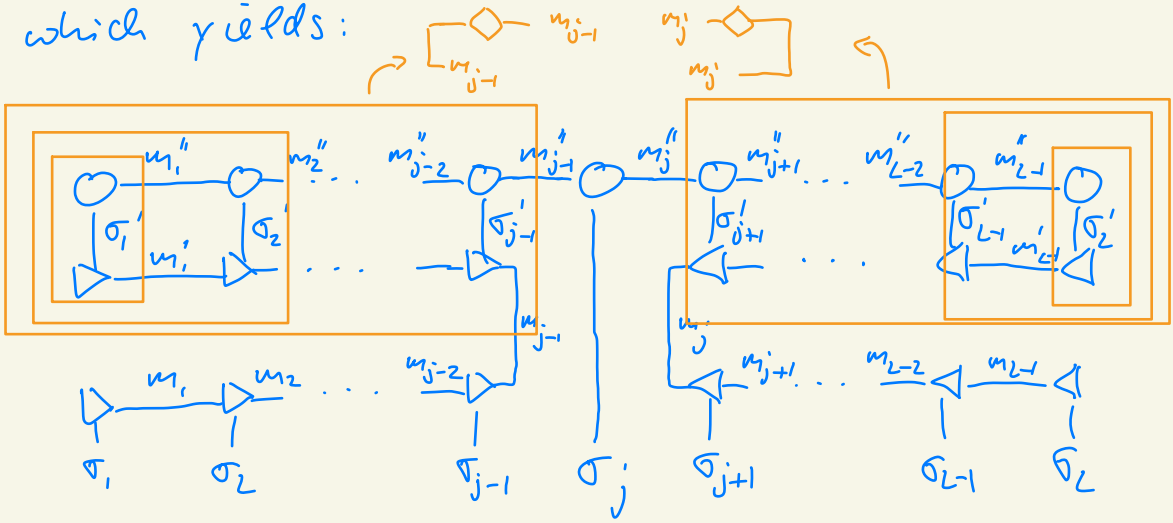
$\hat{\Pi}_j$ can be defined by :



If $\hat{\Pi}_j$ acts on $|\psi\rangle$, then we can use the gauge - trade to show:



which yields:



It is also easy to see that $\hat{\mathbb{T}}_j^2 = \mathbb{1}_j$.

Thus, $\hat{\mathbb{T}}_j$ is the unique operator, which transforms the MPS representation of $|\Psi\rangle$ into the mixed-canonical representation with orthogonality center at site "j".

Variational compression

Assume $|\psi\rangle$ is given as MPS with bond dimensions m_1, \dots, m_{L-1} . We want to approximate $|\psi\rangle$ by a state $|\tilde{\psi}\rangle$ with max. bond dimension \tilde{m} by minimizing the distance:

$$\begin{aligned} \text{dist}(|\psi\rangle, |\tilde{\psi}\rangle) &= \|\psi\rangle - |\tilde{\psi}\rangle\|^2 \\ &= \langle\psi|\psi\rangle + \langle\tilde{\psi}|\tilde{\psi}\rangle - \langle\psi|\tilde{\psi}\rangle - \langle\tilde{\psi}|\psi\rangle \end{aligned}$$

We minimize $\text{dist}(|\psi\rangle, |\tilde{\psi}\rangle)$ by searching the stationary point w.r.t. to all coefficients $\tilde{M}_{\tilde{m}_j-1, \sigma_j}^{\sigma_j}$ of the guess state $|\tilde{\psi}\rangle$:

$$\langle\tilde{\psi}| \equiv \langle\tilde{\psi}(\tilde{M}_{\tilde{m}_1}^{\sigma_1*}, \tilde{M}_{\tilde{m}_1, \tilde{m}_2}^{\sigma_2*}, \dots, \tilde{M}_{\tilde{m}_{L-1}}^{\sigma_L*})|$$

$$\Rightarrow 0 = \left(\frac{\partial}{\partial \tilde{M}_{\tilde{m}_1}^{\sigma_1*}} + \frac{\partial}{\partial \tilde{M}_{\tilde{m}_1, \tilde{m}_2}^{\sigma_2*}} + \dots + \frac{\partial}{\partial \tilde{M}_{\tilde{m}_{L-1}}^{\sigma_L*}} \right) (\langle\tilde{\psi}|\tilde{\psi}\rangle - \langle\tilde{\psi}|\psi\rangle)$$

The scalar products are evaluated by contracting a tensor-network:

$$\langle \hat{\psi} | \psi \rangle = \sum_{\sigma_1} \dots \sum_{\sigma_L} (\underline{\tilde{M}}^{\sigma_L})^\dagger (\underline{\tilde{M}}^{\sigma_{L-1}})^\dagger \dots (\underline{\tilde{M}}^{\sigma_1})^\dagger \underline{M}^{\sigma_1} \dots \underline{M}^{\sigma_{L-1}} \underline{M}^{\sigma_L}$$

Now each derivative "erases" the coefficients

$\tilde{M}_{\tilde{m}_{j-1} \tilde{m}_j}^{\sigma_j}$ it acts on:

$$\frac{\partial}{\partial \tilde{M}_{\tilde{m}_{j-1} \tilde{m}_j}^{\sigma_j}} \langle \hat{\psi} | \psi \rangle =$$

coefficients $\tilde{M}_{\tilde{m}_{j-1} \tilde{m}_j}^{\sigma_j}$ removed from derivative!

However, solving the optimization problem for all derivatives is still hopeless. But we can use the fact $|\hat{\Psi}\rangle = \hat{\Pi}_j |\tilde{\Psi}\rangle$ where now $\hat{\Pi}_j$ is created from the gauge-fixed tensors of $|\tilde{\Psi}\rangle$. We then solve for each $j \in \{1, \dots, L\}$:

$$\frac{\partial}{\partial \hat{\Pi}_{\tilde{m}_{k+1} \tilde{m}_k}^{\sigma_k}} \left(\langle \tilde{\Psi} | \hat{\Pi}_j | \tilde{\Psi} \rangle - \langle \tilde{\Psi} | \hat{\Pi}_j | \Psi \rangle \right) = 0$$

Therefore, we can use the mixed-canonical representation & only solve for one set of coefficients $\hat{\Pi}_{\tilde{m}_{j-1} \tilde{m}_j}^{\sigma_j}$:

$$0 = \tilde{m}_{j-1} \text{---} \textcircled{\sigma_j} \text{---} \tilde{m}_j \text{---} \left[\begin{array}{c} \text{---} m_{j-2} \text{---} \textcircled{m_{j-1}} \text{---} \textcircled{m_j} \text{---} \textcircled{m_{j+1}} \text{---} \dots \\ \sigma_1 \downarrow \quad \downarrow \sigma_{j-1} \quad \sigma_j \downarrow \quad \sigma_{j+1} \downarrow \quad \sigma_2 \downarrow \\ \text{---} \tilde{m}_{j-2} \text{---} \textcircled{\tilde{m}_{j-1}} \text{---} \tilde{m}_j \text{---} \textcircled{\tilde{m}_{j+1}} \text{---} \dots \end{array} \right]$$

$$\Rightarrow \tilde{m}_{j-1} \text{---} \textcircled{\sigma_j} \text{---} \tilde{m}_j = \left[\begin{array}{c} \text{---} m_{j-2} \text{---} \textcircled{m_{j-1}} \text{---} \textcircled{m_j} \text{---} \textcircled{m_{j+1}} \text{---} \dots \\ \sigma_1 \downarrow \quad \downarrow \sigma_{j-1} \quad \sigma_j \downarrow \quad \sigma_{j+1} \downarrow \quad \sigma_2 \downarrow \\ \text{---} \tilde{m}_{j-2} \text{---} \textcircled{\tilde{m}_{j-1}} \text{---} \tilde{m}_j \text{---} \textcircled{\tilde{m}_{j+1}} \text{---} \dots \end{array} \right]$$

The left-hand side is an optimized site-tensor of the approx. $|\tilde{\Psi}\rangle$ & the right-hand side the contractions we have to perform to obtain this optimized tensor. Note that if we sweep from left to right & vice versa, we can obtain optimized tensors, reusing previous contractions of the right side.

Variational ground-state search

We apply the variational principle to find optimal approx. to the solution of the minimization problem:

$$|\tilde{\Psi}_0\rangle = \underset{|\psi\rangle \in \mathcal{M}(m)}{\operatorname{argmin}} \frac{\langle \psi | \hat{H} | \psi \rangle}{\langle \psi | \psi \rangle}$$

where $\mathcal{M}(m)$ is the manifold of MPS with bond

dimensions $\underline{m} = (m_1, m_2, \dots, m_{L-1})$. Introducing a Lagrange-multiplier $\lambda \in \mathbb{R}$, the minimization is equivalent to solve

$$\frac{\partial}{\partial \bar{M}_{m_{j-1} m_j}^{\sigma_j}} \left(\langle \psi | \hat{H} | \psi \rangle - \lambda \langle \psi | \psi \rangle \right) \stackrel{!}{=} 0$$

for all coefficients $\bar{M}_{m_{j-1} m_j}^{\sigma_j}$ of the bra:

$$\langle \psi | = \sum_{\sigma_1, \dots, \sigma_L} \bar{M}^{\sigma_1} \bar{M}^{\sigma_2} \dots \bar{M}^{\sigma_L} \langle \sigma_1, \dots, \sigma_L |$$

We obtain L coupled equations (for each site):

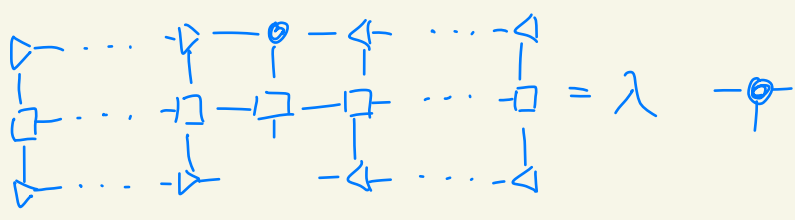
$$\begin{array}{c} |\psi\rangle \\ \hat{H} \\ \langle \psi| \end{array} \begin{array}{c} \circ \cdots \circ \circ \circ \cdots \circ \\ | \cdots | \cdots | \cdots | \cdots | \\ \circ \cdots \circ \circ \circ \cdots \circ \end{array} = \lambda \begin{array}{c} \circ \cdots \circ \circ \circ \cdots \circ \\ | \cdots | \cdots | \cdots | \cdots | \\ \circ \cdots \circ \circ \circ \cdots \circ \end{array} \begin{array}{c} |\psi\rangle \\ \langle \psi| \end{array}$$

$$\text{where } \begin{array}{c} \sigma'_1 \\ | \cdots | \\ \sigma_1 \end{array} \cdots \begin{array}{c} \sigma'_L \\ | \cdots | \\ \sigma_L \end{array} = \sum_{\sigma_1, \dots, \sigma_L} \sum_{\sigma'_1, \dots, \sigma'_L} \underline{\omega}^{\sigma_1 \sigma'_1} \underline{\omega}^{\sigma_2 \sigma'_2} \dots \underline{\omega}^{\sigma_L \sigma'_L} |\sigma_1, \dots, \sigma_L\rangle \langle \sigma'_1, \dots, \sigma'_L|$$

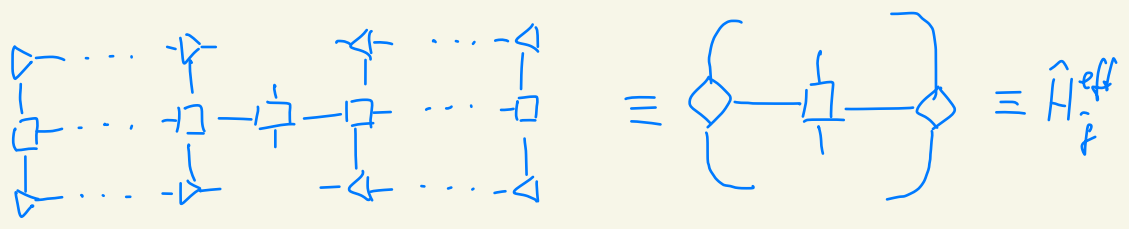
is the representation of \hat{H} as matrix-product operator.

Again, we use the mixed-canonical

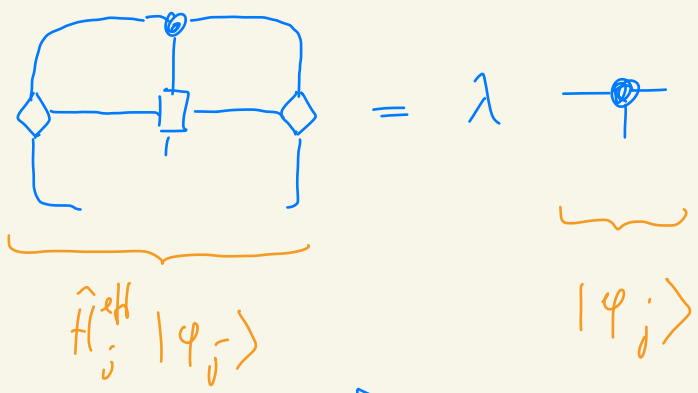
representation to decouple the set of equations:


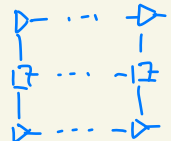


We treat the network:



as operator acting on $|\varphi_i\rangle$. Then we have to solve the local eigenvalue problems:



Note:  =  can be constructed iteratively when sweeping through the system! (51)

Here, a Lanczos algorithm - seems to be the method of choice to find the eigentensor $|\phi\rangle \equiv |q_j\rangle$ & eigenvalue λ yielding an approx. to the overall ground state.

Note:

- Computing $\hat{H}_j^{\text{eff}} |q_j\rangle$ is numerical most expensive operation $\sim \mathcal{O}(m^3 d^2 \omega^2)$ where $\omega \hat{=} \text{MPO-bond dimension}$
- Convergence locally is exponentially fast in the gap of the local Hamiltonian \hat{H}_j^{eff}
- Global convergence in principle also exponential, but: only in the manifold $d\ell(\underline{m})!$
- Global optimization no longer convex

because of $\hat{H} \Rightarrow$ Can get stuck in local minima

- Careful choice of initial guess (ψ) & 2-site updates or algorithms to increase bond-dims is crucial!

MPO - construction (the tale of FSI's)

How do we obtain MPO-representation of \hat{H} ?

Let us look as an example at the transverse field Ising model with $L=2$ sites:

$$\begin{aligned}\hat{H} &= \hat{S}_1^z \hat{S}_2^z - g \hat{S}_1^x - g \hat{S}_2^x \\ &= \hat{S}^z \otimes \hat{S}^z + (-g \hat{S}^x) \otimes \mathbb{1} + \mathbb{1} \otimes (-g \hat{S}^x) \\ &= \begin{pmatrix} \mathbb{1} & \hat{S}^z & -g \hat{S}^x \end{pmatrix} \begin{pmatrix} -g \hat{S}^x \\ \hat{S}^z \\ \mathbb{1} \end{pmatrix}\end{aligned}$$

General idea: Introduce bipartition at site j

$$\begin{aligned} \hat{H} &= \sum_j \hat{S}_j^z \hat{S}_{j+1}^z - g \sum_j \hat{S}_j^x \\ &= \sum_{l < j} \hat{S}_l^z \hat{S}_{l+1}^z + \sum_{l \leq j} (-g \hat{S}_l^x) \\ &\quad + \sum_{\substack{l > j \\ l < L}} \hat{S}_l^z \hat{S}_{l+1}^z + \sum_{l > j} (-g \hat{S}_l^x) \\ &\quad + \hat{S}_j^z \hat{S}_{j+1}^z + (-g \hat{S}_j^x) \end{aligned}$$

Denote:

$$\hat{H}_{<j}^\alpha = \hat{h}_{<j}^\alpha \otimes \mathbb{1}^{\otimes L-j+1} \quad \text{where } \hat{h}_{<j}^\alpha \in \mathcal{H}_{<j} \text{ acts only on sites } 1 \dots j-1$$

$$\hat{H}_{>j}^\alpha = \mathbb{1}^{\otimes j} \otimes \hat{h}_{>j}^\alpha \quad \text{where } \hat{h}_{>j}^\alpha \in \mathcal{H}_{>j} \text{ acts only on sites } j+1 \dots L$$

Identify:

$$\hat{h}_{<j}^L = \sum_{l < j} \hat{S}_l^z \hat{S}_{l+1}^z + \sum_{l < j} (-g \hat{S}_l^x) \quad \text{acting only on left part of system}$$

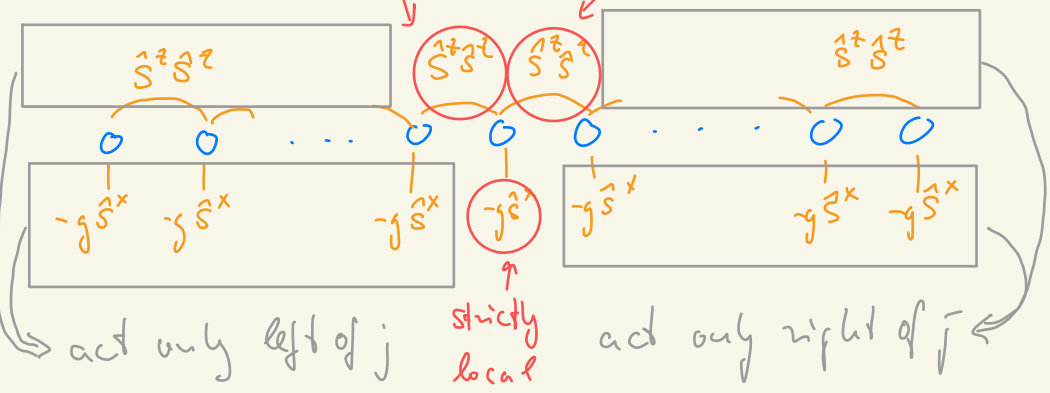
$$\hat{h}_{>j}^R = \sum_{l>j} \hat{S}_l^z \hat{S}_{l+1}^z + \sum_{l>j} (-g \hat{S}_l^x)$$

$$\hat{h}_{<j}^{zz} = \hat{S}_{j-1}^z, \quad \hat{h}_{>j}^{zz} = \hat{S}_{j+1}^z$$

Then we can write:

$$\hat{H} = \left(\mathbb{1}^{\otimes (j-1)} \quad \hat{h}_{<j}^{zz} \quad \hat{h}_{<j}^L \right) \begin{pmatrix} \mathbb{1} & \hat{S}^z & (-g \hat{S}^x) \\ 0 & 0 & \hat{S}^z \\ & & \mathbb{1} \end{pmatrix} \begin{pmatrix} \hat{h}_{>j}^R \\ \hat{h}_{>j}^{zz} \\ \mathbb{1} \end{pmatrix}$$

Interpretation: open operator strings connecting left/right part with site j



we have:

(i) complete operator strings in left/right part of the system

(ii) open operator strings connecting left/right 95

part of system with site j

(iii) strictly local operators

Systematic formulation using finite state machines (FSMs)

An operator is completely characterized by all non-trivial, distinct strings of local operators.

Treat operator strings (e.g. $\mathbb{1} \otimes \dots \otimes \hat{S}^z \otimes \hat{S}^z \otimes \mathbb{1} \otimes \dots$) as "words" formed by "alphabet" Σ , (e.g. for spins: $\Sigma = \{\mathbb{1}, \hat{S}^x, \hat{S}^y, \hat{S}^z\}$). A global operator \hat{H} is then defined by the set of "words" compatible with \hat{H} .

Finite state machine:

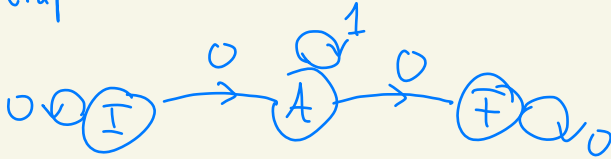
For Σ , a set of symbols & Ω a set of states

then $\delta : \Sigma \times \Omega \rightarrow \Omega$ an invertible map defines a FSM.

Example

Which transition function δ generates all possible combinations of $0 \dots 0 1 \dots 1 0 \dots 0$ with at arb. amount of "1" between arbitrary amount of '0'?

Graphical solution:



$$\Sigma = \{0, 1\}$$

$$\Omega = \{I, A, F\}$$

$$\delta[I, 0] \mapsto I$$

$$\delta[A, 0] \mapsto A$$

$$\delta[A, 1] \mapsto F$$

$$\delta[I, 1] \mapsto A$$

$$\delta[F, 0] \mapsto F$$

Write δ as matrix:

$$\begin{array}{c} \begin{array}{ccc} & I & A & F \\ I & \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \\ A & \\ F & \end{array} \end{array}$$

Now any sequence of length "L" is obtained by formally multiplying matrices:

$$L = 4:$$

$$(0 \ 0 \ 0) \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$= (00 \ 00+01 \ 00) \begin{pmatrix} 00 \\ 10+00 \\ 00 \end{pmatrix} = 0000 + 0010 + 0100 + 0110 + 0000$$

Now let's apply this to operators!

$$\text{Consider } \hat{H} = \sum_j (\hat{S}_j^x \hat{S}_j^x + \hat{S}_j^y \hat{S}_j^y + \hat{S}_j^z \hat{S}_j^z).$$

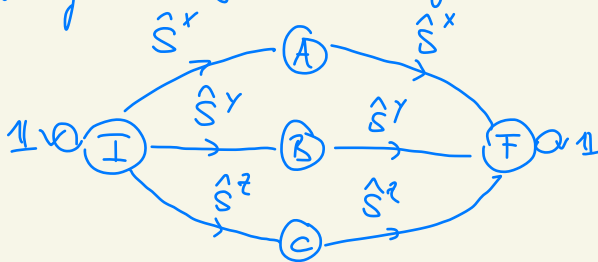
There are 3 types of operator strings:

$$a) \mathbb{1} \otimes \dots \otimes \mathbb{1} \otimes \hat{S}^x \hat{S}^x \otimes \mathbb{1} \otimes \dots \otimes \mathbb{1}$$

$$b) \mathbb{1} \otimes \dots \otimes \mathbb{1} \otimes \hat{S}^y \hat{S}^y \otimes \mathbb{1} \otimes \dots \otimes \mathbb{1}$$

$$c) \mathbb{1} \otimes \dots \otimes \mathbb{1} \otimes \hat{S}^z \hat{S}^z \otimes \mathbb{1} \otimes \dots \otimes \mathbb{1}$$

They are generated by the FSM:



$$\Sigma = \{\mathbb{1}, \hat{S}^x, \hat{S}^y, \hat{S}^z\}$$

$$\Omega = \{I, A, B, C, F\}$$

Transition function as operator-valued matrix:

$$\underline{\underline{\hat{W}}} = \begin{pmatrix} \mathbb{1} & \hat{S}^x & \hat{S}^y & \hat{S}^z & 0 \\ 0 & 0 & 0 & 0 & \hat{S}^x \\ 0 & 0 & 0 & 0 & \hat{S}^y \\ 0 & 0 & 0 & 0 & \hat{S}^z \\ 0 & 0 & 0 & 0 & \mathbb{1} \end{pmatrix} \begin{matrix} \Gamma \\ A \\ B \\ C \\ F \end{matrix}$$

$$\begin{matrix} \Gamma \\ A \\ B \\ C \\ F \end{matrix}$$

at lattice site j take expectation value:

$$\underline{\underline{W}}_{\sigma_j \sigma_j'} = \langle \sigma_j | \underline{\underline{\hat{W}}} | \sigma_j' \rangle$$

$$= \begin{pmatrix} \langle \sigma_j | \mathbb{1} | \sigma_j' \rangle & \langle \sigma_j | \hat{S}^x | \sigma_j' \rangle & \langle \sigma_j | \hat{S}^y | \sigma_j' \rangle & \langle \sigma_j | \hat{S}^z | \sigma_j' \rangle & 0 \\ & & & & \langle \sigma_j | \hat{S}^x | \sigma_j' \rangle \\ & & & & \langle \sigma_j | \hat{S}^y | \sigma_j' \rangle \\ & & & & \langle \sigma_j | \hat{S}^z | \sigma_j' \rangle \\ & & & & \langle \sigma_j | \mathbb{1} | \sigma_j' \rangle \end{pmatrix}$$

4x4

MPO-matrix at site j !

From this construction scheme, any operator on \mathcal{H}_L can be converted into an MPO by constructing the matrices $\underline{\omega}^{g_j \sigma_j}$ explicitly.