

Neutrino Physics Course

Lecture XVII

23/6/2023

LMU

Summer 2021



LRS M: (even) mwe on SSB

- first stage: LR scale!

$$G_{LR} = SU(2)_L \times SU(2)_R \times U(1)_{BL}$$

$$\downarrow \langle \Delta_R \rangle$$

$$SU(2)_L \times U(1)$$

$$V = -\underline{\mu_\Delta}^2 (T_L \Delta_L^\dagger \Delta_L + T_R \Delta_R^\dagger \Delta_R)$$

$$+ \frac{\lambda_1}{4} \left[(T_L \Delta_L^\dagger \Delta_L)^2 + (T_R \Delta_R^\dagger \Delta_R)^2 \right]$$

$$+ \frac{\lambda_2}{2} \left[T_L \Delta_L^2 T_R (\Delta_L^\dagger)^2 + L \leftrightarrow R \right]$$

$$+ \frac{\lambda_3}{2} T_L \Delta_L^\dagger \Delta_L T_R \Delta_R^\dagger \Delta_R$$

$$+ \frac{\lambda_4}{2} (T_L \Delta_L^2 T_R \Delta_R^{+2} + L \leftrightarrow R)$$

Maiese et al '16

$$\langle \Delta_L \rangle = 0, \quad \langle \Delta_R \rangle = \begin{pmatrix} 0 & 0 \\ v_R & 0 \end{pmatrix}$$

$$\Delta_L = \begin{pmatrix} f_L^+ & f_L^{++} \\ f_L^0 & -f_L^+ \end{pmatrix}$$

$$\Delta_R = \begin{pmatrix} -f_R^+ & f_R^{++} \\ \vdots & \vdots \\ v_R + H_R + iG_R & -f_R^+ \end{pmatrix}$$

eaten by w_R^+

↑
eaten by z_R

$(\lambda_1 > 0, \lambda_2 > 0)$

$$m_{H_R}^2 = 2 \lambda_1 \vartheta_R^2$$

$$m_{\delta_{R++}}^2 \propto \lambda_2 \vartheta_R^2$$

ϑ_R
vector

\Downarrow

Check *

$$m_{\Delta_L}^2 = m_{\delta_L^+}^2 = m_{\delta_L^{++}}^2 \propto (\lambda_1 - \lambda_3) \vartheta_R^2$$

$$m_{\Delta_L}^2 \propto (\lambda_1 - \lambda_3) \vartheta_R^2$$

(> 0)

explicit

$$v_L = 0, \quad v_R \neq 0$$



$$SU(2)_L \times SU(2)_R \times U(1)_{B-L}$$

$$\downarrow \quad \frac{Y}{2} = T_{3R} + \frac{B-L}{2}$$
$$SU(2)_R \times U(1)_Y$$

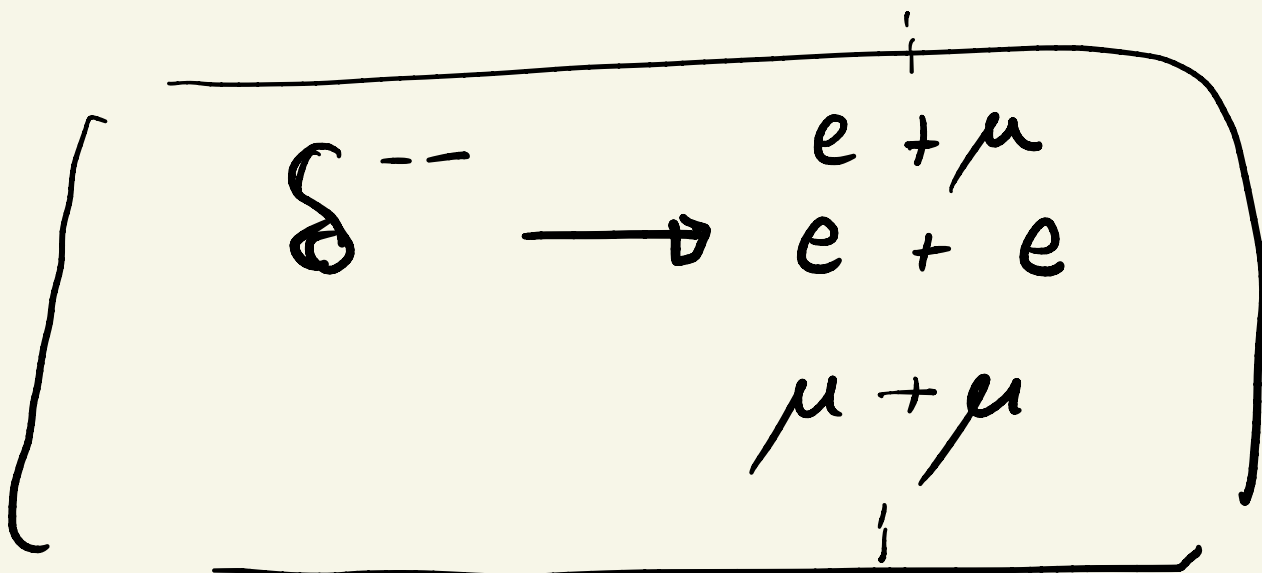
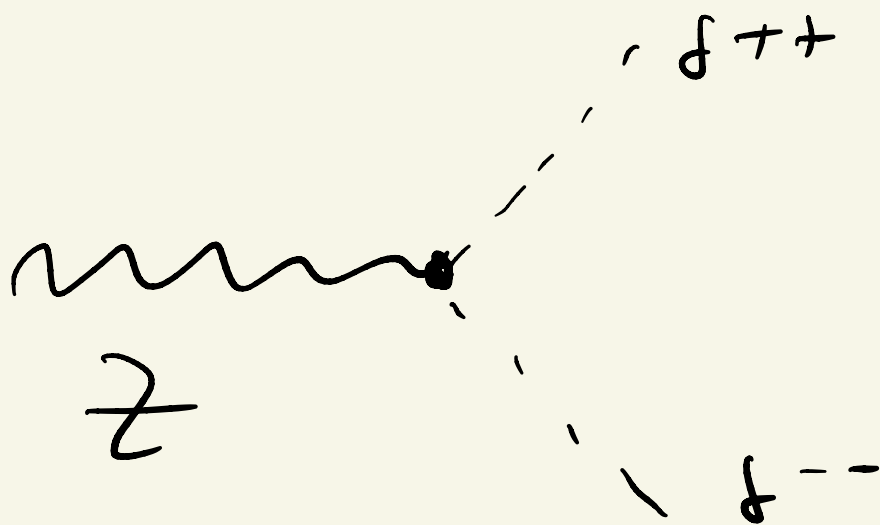
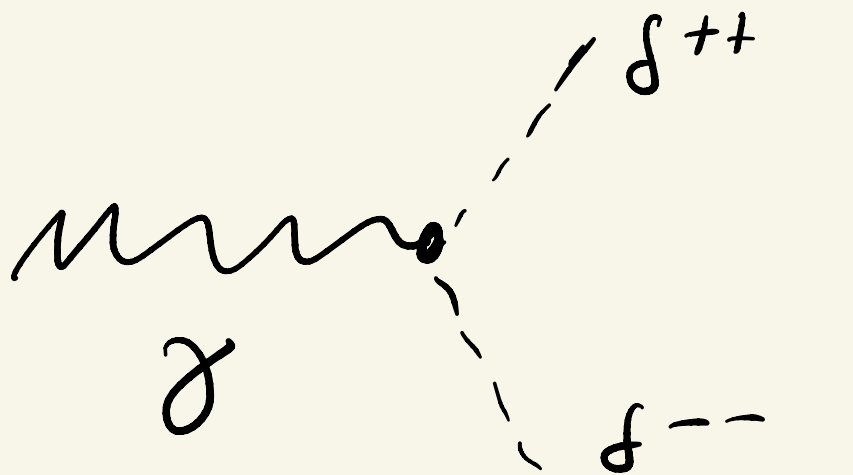
unbroken !!!

LHC: $M_{S_L^{++}}, M_{S_R^{++}} \gtrsim 400 \text{ GeV}$

\downarrow theory

|| $M_{S_L^+} \gtrsim 400 \text{ GeV}$ |

$M_{\delta^0} \gtrsim 400 \text{ GeV}$ //



- next stage: weak scale

$$SU(2)_L \times U(1)_Y \xrightarrow{\langle \phi \rangle} U(1)_{em}$$

SM Higgs doublet

$$\phi \subseteq \Phi \longrightarrow U_L \Phi U_R^\dagger \quad \tilde{\Phi} \equiv i\sigma_2 \phi^*$$

$$\Phi = \begin{pmatrix} \tilde{\phi}_1 & \phi_2 \end{pmatrix} = \begin{pmatrix} \phi_1^{0*} & \phi_2^+ \\ -\phi_1^- & \phi_2^0 \end{pmatrix}$$

Let's study Φ

$\Phi = 2 \times 2$ matrix

$$\hookrightarrow U_L \Phi U_R^\dagger$$

reminder: $H \rightarrow U H U^\dagger$ ($H = H^\dagger$)

$H \rightarrow$ diagonalize

M (general $n \times n$)

\Downarrow

$$U_L M U_R^\dagger = \text{diagonal}$$

\Downarrow

$$\underline{\Phi} \rightarrow \begin{pmatrix} r_1 e^{i d_1} & 0 \\ 0 & r_2 e^{i d_2} \end{pmatrix}$$

still!

$$U_L = \begin{pmatrix} e^{i d_L} & 0 \\ 0 & e^{-i d_L} \end{pmatrix}$$

$$U_R = \begin{pmatrix} e^{i d_R} & 0 \\ 0 & e^{-i d_R} \end{pmatrix}$$



$$\underline{\Phi} \rightarrow \begin{pmatrix} r_1 e^{i(\alpha_L - \alpha_R + d_1)} & 0 \\ 0 & r_2 e^{-i(d_L - \alpha_R - \alpha_2)} \end{pmatrix}$$

$$\therefore \alpha_L - \alpha_R = -\alpha_1$$

$$\underbrace{\Phi}_{\text{(basis)}} \rightarrow \begin{pmatrix} \nu_1 & & 0 \\ & & \\ 0 & & \nu_2 e^{i\alpha} \end{pmatrix}$$



3 invariants

$$\tilde{\Phi} = \sigma_2 \Phi^* \sigma_2$$

(i) $\text{Tr} \Phi^+ \Phi$:

$$\Phi \rightarrow U_L \Phi U_R^T$$

$$\Phi^+ \rightarrow U_R \Phi^+ U_L^T$$

(ii) $\text{Tr} \Phi^+ \Phi \Phi^+ \Phi$

$$\tilde{\Phi} \rightarrow U_L \tilde{\Phi} U_R^T$$

$$(iii) \operatorname{Tr} \tilde{\Phi}^+ \bar{\Phi}, \quad (iv) \operatorname{Tr} \bar{\Phi}^+ \tilde{\Phi}$$

$$(v) \det \bar{\Phi}, \quad (vi) (\det \bar{\Phi})^*$$

↓ 3 independent

$$(a) \operatorname{Tr} \bar{\Phi}^+ \bar{\Phi}, \quad \det \bar{\Phi}, \quad \det \bar{\Phi}^*$$

4

$$(b) \operatorname{Tr} \bar{\Phi}^+ \bar{\Phi}, \quad \operatorname{Tr} \tilde{\Phi}^+ \bar{\Phi}, \quad \operatorname{Tr} \bar{\Phi}^+ \tilde{\Phi}$$

$$(a) \Leftrightarrow (b) \Leftarrow \operatorname{Tr} \tilde{\Phi}^+ \bar{\Phi} = 2 \det \bar{\Phi}$$

$$V_{\Phi} = \left(-\frac{\mu_{\phi}^2}{2} \right) T_{\nu} \Phi + \Phi \left(\frac{\bar{\mu}_{\phi}^2}{2} \right) T_{\nu} \tilde{\Phi} + \Phi \quad (+h.c.)$$

$$+ \frac{\lambda_{\phi}}{4} (T_{\nu} \Phi + \Phi)^2 \leftarrow \text{trivial inv.}$$

$$+ \frac{\lambda_{\phi}'}{4} T_{\nu} \Phi + \Phi (T_{\nu} \tilde{\Phi} + \Phi + h.c.)$$

$$+ \frac{\lambda_{\phi}''}{4} T_{\nu} \tilde{\Phi} + \Phi T_{\nu} \Phi + \tilde{\Phi}$$

$$+ \frac{\lambda_{\phi}'''}{4} T_{\nu} \Phi + \Phi \tilde{\Phi} + \Phi$$



$$\tilde{\Phi}^+ \Phi = \frac{1}{2} (\text{Tr} \tilde{\Phi}^+ \Phi) \mathbb{1}$$

$$(v_i v_i) \text{Tr} \Phi^+ \Phi \tilde{\Phi}^+ \Phi =$$

$$= \frac{1}{2} \underbrace{\text{Tr} \Phi^+ \Phi}_{\text{Tr}} \underbrace{\text{Tr} \tilde{\Phi}^+ \Phi}_{\text{Tr}}$$

example adjoint of $SU(n)$

$$\Sigma \rightarrow U \Sigma U^+$$

$$(\Sigma^+ = \Sigma, \text{Tr} \Sigma = 0)$$



$\Sigma \rightarrow$ diagonal

(a) $\underline{SU(2)} \Rightarrow \Sigma_{2 \times 2} \rightarrow \text{diag}(\varphi, -\varphi)$



1 invariant = $T_1 \Sigma^2$

(b) $SU(3) \Rightarrow \Sigma_{3 \times 3} \rightarrow \text{diag}(\varphi_1, \varphi_2, -(\varphi_1 + \varphi_2))$

2 invariants = $T_1 \Sigma^2, T_1 \Sigma^3$

$$T_1 \Sigma^4 = \varphi_1^4 + \varphi_2^4 + (\varphi_1 + \varphi_2)^4$$

$$= \varphi_1^4 + \varphi_2^4 + (\varphi_1^4 + 4\varphi_1^3\varphi_2 + 6\varphi_1^2\varphi_2^2 + \dots)$$

$$+ 4\varphi_1\varphi_2^3 + \varphi_2^4)$$

$$= 2\varphi_1^4 + 2\varphi_2^4 + 4\varphi_1^3\varphi_2 + 6\varphi_1^2\varphi_2^2 + 4\varphi_1\varphi_2^3$$

$$i. \quad T_v \Sigma^2 = \varphi_1^2 + \varphi_2^2 + (\varphi_1 + \varphi_2)^2$$

$$= 2\varphi_1^2 + 2\varphi_2^2 + 2\varphi_1\varphi_2$$

$$\Rightarrow \boxed{2(\varphi_1^2 + \varphi_2^2 + \varphi_1\varphi_2) = T_v \Sigma^2}$$

$$ii. \quad T_v \Sigma^3 = \varphi_1^3 + \varphi_2^3 - (\varphi_1 + \varphi_2)^3$$

$$= \cancel{\varphi_1^3} + \cancel{\varphi_2^3} - \cancel{\varphi_1^3} - \cancel{\varphi_2^3} - 3\varphi_1^2\varphi_2 - 3\varphi_1\varphi_2^2$$

$$\Rightarrow \boxed{-3\varphi_1\varphi_2(\varphi_1 + \varphi_2) = T_v \Sigma^3}$$

$$\text{Tr } Z^4 = 2\psi_1^4 + 2\psi_2^4 + 2\psi_1^3\psi_2 + 2\psi_1\psi_2^3$$

$$+ 6\psi_1^2\psi_2^2 + 2\psi_1^3\psi_2 + \dots$$

$$= 2(\psi_1^3 + \psi_2^3)(\psi_1 + \psi_2) + \dots$$



$$\text{Tr } Z^4 = f(\text{Tr } Z^2) + f'(\text{Tr } Z^3)$$

~~$\text{Tr } Z^2 \cdot \text{Tr } Z^3$~~

$$\text{Tr } Z^4 = \frac{1}{2} (\text{Tr } Z^2)^2$$

$$\text{Tr } Z^5 \propto \text{Tr } Z^3 \text{Tr } Z^2 \text{ Claim!}$$

(c) SU(4)

$$\Sigma \rightarrow \text{diag} (\varphi_1, \varphi_2, \varphi_3, -(\varphi_1 + \varphi_2 + \varphi_3))$$

⇓ invariants (3)

$$(T_r \Sigma^2, T_r \Sigma^3, T_r \Sigma^4)$$

⇓

$$T_r \Sigma^5 \propto T_r \Sigma^2 T_r \Sigma^3$$

(d) SU(5) \cong SU(3) \times SU(2) \times U(1)

$$\Sigma \rightarrow \text{diag} (\varphi_1, \varphi_2, \varphi_3, \varphi_4, -(\sum_{i=1, \dots, 4} \varphi_i))$$

⊗ 4 inv. ⇓

$$T_V \Sigma^2, T_V \Sigma^3, T_V \Sigma^4, T_V \Sigma^5$$

⇓

$$T_V \Sigma^6 = a(T_V \Sigma^2)^2 + b(T_V \Sigma^3)^2 + c T_V \Sigma^2 T_V \Sigma^4 + \dots$$

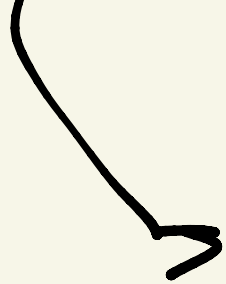
(Δ, Φ) system

$$V = V_\Delta + V_\Phi + \underbrace{V_{\Delta, \Phi}}_{\text{new}}$$

SSB

Used $SU(2)_R$ ($+ \lambda_2 > 0$) \therefore

$$\langle \Delta \rangle = \begin{pmatrix} 0 & 0 \\ v_R & 0 \end{pmatrix}$$



I cannot use $SU(2)_R$

any more

$$\Phi \rightarrow v_L \Phi v_R^T$$



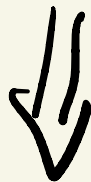
no freedom

any more



$\langle \Phi \rangle \neq \text{diag}$ (cannot be argued)

$$\Phi = \begin{pmatrix} \varphi_1^{0*} & \varphi_2^+ \\ -\varphi_1^- & \varphi_2^0 \end{pmatrix}$$



$$\langle \Phi \rangle = \begin{pmatrix} v_1 & 0 \\ 0 & v_2 e^{i\alpha} \end{pmatrix}$$

in order that $\Delta Q_{em} = 0$

$$V_{\Phi \Delta} = \alpha_1 T_\nu \Phi^\dagger \Phi (T_\nu \Delta_L^\dagger \Delta_L + L \leftrightarrow R)$$

$$+ \alpha_2 (T_\nu \tilde{\Phi}^\dagger \Phi \text{ (h.c.)}) \quad \left(\begin{array}{c} - \\ \parallel \\ - \end{array} \right)$$

$$+ \alpha_3 (T_\nu \Delta_R^\dagger \Phi + \Phi \Delta_R + R \rightarrow L)$$

$$+ \alpha_4 T_V \Delta_R^\dagger \tilde{\Phi}^\dagger \bar{\Phi} \Delta_R$$

||

$$\frac{1}{2} \alpha_4 T_V \Delta_R^\dagger \Delta_R T_V \tilde{\Phi}^\dagger \bar{\Phi} \quad (\alpha_2)$$

$$\langle \Phi \rangle = \begin{pmatrix} v_1 & 0 \\ 0 & v_2 e^{i\alpha} \end{pmatrix}$$

$$M_w^2 = \frac{g^2}{4} (v_1^2 + v_2^2)$$

$$M_z^2 \cos^2 \theta_w = M_w^2$$

~~≠~~ bottom line

ϕ_1, ϕ_2 $(d=0)$ 

$$\tan \psi \equiv v_2/v_1$$

$$h = \cos \psi \phi_1 + \sin \psi \phi_2$$

$$H = -\sin \psi \phi_1 + \cos \psi \phi_2$$

$$\langle h \rangle = \sqrt{v_1^2 + v_2^2}$$

$$\langle H \rangle = 0$$

$$\Rightarrow \left[\begin{array}{l} M_h^2 \propto M_w^2 \\ M_H^2 \propto M_A^2 \end{array} \right]$$

To be proven (stay tuned?)